

Model Question Paper-2 with effect from 2019-20 (CBCS Scheme)

USN

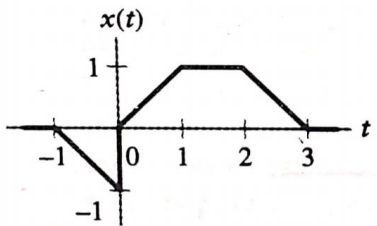
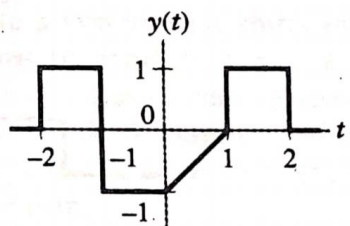
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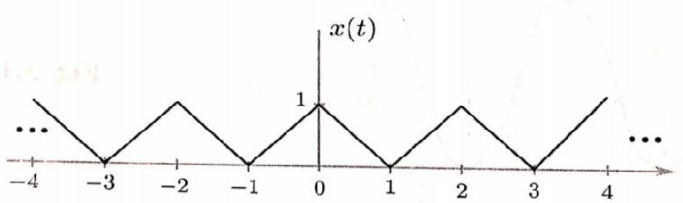
Fourth Semester B.E. Degree Examination Signals and Systems

TIME: 03 Hours

Max. Marks: 100

- Note: 01. Answer any **FIVE** full questions, choosing at least **ONE** question from each **MODULE**.
02. Short forms used take usual meaning.
03. Missing data may be suitably assumed.

Module -1			*Bloom's Taxonomy Level	Marks
Q.01	a	Given the signal $x[n] = (8 - n)(u[n] - u[n - 7])$, sketch the following signals: (i) $y[n] = x[4 - n]$ (ii) $g[n] = x[-2n + 3]$	L2	4 Marks
	b	Calculate the Energy and Power of the following signals: (i) $x(t) = e^{-0.05t}[u(t) - u(t - 10)]$ (ii) $x[n] = u[n]$ (iii) $x(t) = 5 \cos(200\pi t)$ (iv) $x[n] = (-2)^n[u(n + 1) - u(n - 2)]$	L3	10 Marks
	c	Find whether the following signals are periodic or not. If periodic, find the fundamental period. (i) $x(t) = \sin^2(400\pi t)$ (ii) $x(t) = \cos(2t) + \sin(3t)$ (iii) $x(t) = \sin(4\pi t) + \sin(5t)$	L2	6 Marks
OR				
Q.02	a	Fig. Q2(a) shows two signals $x(t)$ and $y(t)$. Sketch the following signals. (i) $x(t)y(t - 1)$ (ii) $x(t + 1)y(t - 2)$ (iii) $x(t)y(-1 - t)$ (iv) $x(4 - t)y(t)$	L3	10 Marks
		 <p style="text-align: center;">Fig. Q2(a)-(i)</p>  <p style="text-align: center;">Fig. Q2(a)-(ii)</p>		
	b	Evaluate the expression, $\int_1^2 t^2 \delta(2t - 3) dt + \int_{-3}^3 \delta(3t + 5) dt$	L2	4 Marks
	c	Given the signal, $x(t) = r(t + 5) - r(t + 4) - r(t - 4) + r(t - 5)$, sketch $x(t)$ and its derivative.	L3	6 Marks
Module-2				
Q. 03	a	Determine whether the following system represented by input-output relation, is (i) Stable (ii) Memoryless (iii) Causal (iv) Time-invariant and (v) Linear: $y(t) = \int_{-\infty}^t x(\tau) d\tau$	L2	6 Marks

	b	Following represents the input-output relations of various systems. Determine whether they are invertible or not: (i) $y[n] = n x[n]$ (ii) $y(t) = x(2t + 3)$ (iii) $y[n] = \sum_{k=-\infty}^n x[k]$ If Invertible, represent the Inverse system.	L2	6 Marks																		
	c	Let $x[n] = u[n] - u[n - 5]$, be the input signal applied to a Linear and Time-Invariant (LTI) discrete-time system and $h[n] = \alpha^n (u[n] - u[n - 7])$, be the impulse response of the system. Obtain the output signal, $y[n]$.	L3	8 Marks																		
OR																						
Q.04	a	Perform convolution operation on the following signals: $x_1(t) = e^{- t-2 }$ and $x_2(t) = e^{-2t}u(t + 4)$	L3	8 Marks																		
	b	Given $x[n] = \{1, 2, 3, -2\}$, here sample-value 2 appears at time-origin, and $h[n] = \delta[n + 1] - 2\delta[n] + 3\delta[n - 1]$. Obtain $y[n] = x[n]*h[n]$.	L3	4 Marks																		
	c	Determine whether the following systems represented by input-output relations are stable and causal: (i) $y[n] = x[n] u[n + 1]$ (ii) $y(t) = x(\sin t)$ (iii) $y[n] = \cos(x[n])$ (iv) $y(t) = t x(t)$	L2	8 Marks																		
Module-3																						
Q. 05	a	Given the impulse response, $h[n]$, of an LTI system, obtain the condition which needs to be satisfied by $h[n]$, for the system to be (i) causal (ii) stable.	L2	4 Marks																		
	b	The signal, $h(t) = u(t) - 2u(t - 1) + u(t - 2)$, represents impulse response of an LTI system. Obtain the step response of the system.	L3	6 Marks																		
	c	Find the complex Fourier Series coefficients $X(k)$ for the waveform shown in the Fig.Q5(c). Sketch magnitude and phase spectra.	L3	10 Marks																		
 <p style="text-align: center;">Fig. Q5(c)</p>																						
OR																						
Q. 06	a	State and prove the following properties of Continuous-Time Fourier Series: (i) Frequency shifting (ii) Time differentiation	L2	6 Marks																		
	b	For a periodic signal $x(t)$, magnitude and phase spectral sample values are given below in the table Q6(b). They take zero values for other values of k . Determine the signal $x(t)$, whose fundamental frequency, $\omega_0 = \pi$ rad/sec.	L3	6 Marks																		
<table border="1" data-bbox="494 1612 957 1758"> <tbody> <tr> <td>k</td> <td>-2</td> <td>-1</td> <td>0</td> <td>1</td> <td>2</td> </tr> <tr> <td>$X(k)$</td> <td>2</td> <td>1</td> <td>1</td> <td>1</td> <td>2</td> </tr> <tr> <td>$\theta(k)$</td> <td>$-\pi/8$</td> <td>$\pi/4$</td> <td>0</td> <td>$\pi/4$</td> <td>$\pi/8$</td> </tr> </tbody> </table> <p style="text-align: center;">Table Q6(b)</p>					k	-2	-1	0	1	2	$ X(k) $	2	1	1	1	2	$\theta(k)$	$-\pi/8$	$\pi/4$	0	$\pi/4$	$\pi/8$
k	-2	-1	0	1	2																	
$ X(k) $	2	1	1	1	2																	
$\theta(k)$	$-\pi/8$	$\pi/4$	0	$\pi/4$	$\pi/8$																	
	c	Determine whether the following systems represented by impulse responses are stable and causal: (i) $h[n] = u[n - 1] - u[n - 5]$ (ii) $h[n] = 0.5^{ n }$ (iii) $h(t) = e^{-t}u(-t)$ (iv) $h(t) = u(t - 1)$	L2	8 Marks																		

Module-4			
Q. 07	a	Show that for a real-valued aperiodic signal $x(t)$, the real part of its Fourier transform is an even function of frequency and the imaginary part is an odd function of frequency.	L2 6 Marks
	b	State and prove the following properties with respect to DTFT: (i) Frequency differentiation (ii) Time-domain Convolution	L2 6 Marks
	c	Find the Fourier Transform of the following signals: (i) $x(t) = \delta(t + 1) - \delta(t - 1)$ (ii) $x(t) = \frac{d}{dt} [te^{-2t} \sin u(t)]$	L3 8 Marks
OR			
Q. 08	a	Find the DTFT of $x[n] = a^{ n }$, $ a < 1$. Also, sketch the magnitude and phase spectra.	L3 6 Marks
	b	State and prove the following properties with respect to continuous-time Fourier transform: (i) Time scaling (ii) Integration	L2 6 Marks
	c	The DTFT of a real signal is $X(e^{j\Omega})$. Express DTFT of each of the following signals in terms of $X(e^{j\Omega})$: (i) $x[-n]$ (ii) $x[n] * x[-n]$ (iii) $(-1)^n x[n]$ (iv) $(1 + \cos n\pi)x[n]$	L3 8 Marks
Module-5			
Q. 09	a	What is Region of Convergence (ROC) of Z-Transform? Mention its properties.	L1 6 Marks
	b	Determine the z-transform and ROC for the following time signals. Sketch the ROC, poles and zeroes in the z-plane. (i) $x[n] = 2^n \sin\left(\frac{\pi}{4}n\right) u[-n]$ (ii) $x[n] = \left(\frac{1}{4}\right)^n (u[n] - u[n - N])$	L3 8 Marks
	c	Find the Inverse Z-transform of $X(z) = \frac{z^4 + z^2}{z^2 - 0.75z + 0.125}$, ROC: $ z > 0.5$, using partial fraction method.	L3 6 Marks
OR			
Q. 10	a	A discrete LTI system is characterized by following Difference equation: $y[n] = y[n-1] + y[n-2] + x[n-1]$ (i) Find the system function. (ii) Indicate ROC if system is stable. (iii) Indicate ROC if system is causal. (iv) Obtain impulse response in both cases.	L3 10 Marks
	b	State and prove the following properties of Z-transform: (i) Time-reversal (ii) Multiplication by exponential function	L2 4 Marks
	c	Find the Z-transform of the following signals: (i) $x[n] = 2^n u[-n - 3]$ (ii) $x[n] = \sin\left(\frac{\pi n}{8} - \frac{\pi}{4}\right) u[n - 2]$	L3 6 Marks

*Bloom's Taxonomy Level: Indicate as L1, L2, L3, L4, etc. It is also desirable to indicate the COs and POs to be attained by every bit of questions.